Calculation of Ball Trajectories With and Without The Effect of Air Resistance

David Wachenschwanz

Equations of Motion for A Trajectory Equations of Motion for A Trajectory Without Air Resistance

 \bullet **■** The flight of a projectile with initial velocity *v*_o initial angle θ (with respect to horizontal) is described by the following sets of equations (neglecting air resistance):

Where

 $v_{o,x}$ = v_o *cos θ, v_{o,y} = v_o sin θ* and the acceleration of gravity *g* = 9.81 m/s²

 \bullet Thus, there is an analytical solution for the position as a function of time

Equations of Motion for A Trajectory Equations of Motion for A Trajectory **Including Air Resistance**

- \bullet **■** The flight of a projectile with initial velocity *ν*_ο initial angle *θ* (with respect to horizontal) is described by the following sets of equations (including air resistance):
- \bullet Horizontal Motion Vertical Motion

$$
\frac{dv_x}{dt} = \frac{f_{drag,x}(t, v_x)}{m}
$$

$$
\frac{dx}{dt} = V_x(t)
$$

Where the force of drag

$$
\frac{dv_y}{dt} = a_y = \frac{f_{drag,y}(t, v_y)}{m}
$$

$$
\frac{dy}{dt} = v_y(t)
$$

v=*velocity A*=*cross* – sectional area = $\frac{1}{4}$ πd^2 for a sphere ρ = density of \emph{air} =1.225 kg / m^3 at sea level where $C_{_d}$ = numerical drag coefficient \approx 0.5 for a sphere $f_{drag}(t) = -\frac{1}{2}C_d \rho A v^2$

A numerical solution of the differential equations must be used to get the position information (I used a C++ program to solve them using a 4th order Runga-Kutta method)

Minimum and Maximum Ranges To Fire The Ball At Goal Minimum and Maximum Ranges To Fire The Ball At Goal

vo = 12 m/s, ball diameter = 7", mass of ball = 185 g

Assuming that we would like to used a fixed launch angle to minimize the complications of making adjustments on the fly in the competition, we set the fixed angle such that the peak height of the trajectory allows the ball to pass just below the top of the goal. We can then calculate the minimum and maximum range from which to shoot the ball and still clear the goal. Here are these ranges with and without the effects of air resistance for various heights for the launcher.

Calculation of The Range That Ball Will Travel With and Without Air Resistance When $\bm{\theta}$ **= 30˚**

vo = 12 m/s, ball diameter = 7", mass of ball = 185 g

From section 4.3.1 of the 2006 FIRST Robotics Competition Documents:

<S02> Muzzle Velocity - No ROBOT may throw a ball with an exit velocity of greater than 12 m/s (26.8 mph). As a reference, a ball traveling at this velocity when leaving the ROBOT at an *angle of 30º* from horizontal with no spin *will travel approximately 35 feet*. A robot that violates this rule will be considered unsafe per <S01>.

Thus, my numerical simulation that included air drag appears to be in agreement with the expectations from FIRST

Optimal Trajectory Without Air Resistance

vo = 12 m/s, θ = 25.5 degrees, height of launcher = 60"

References

- \bullet Trajectory equations ignoring air resistance: http://hyperphysics.phy-astr.gsu.edu/hbase/traj.html
- \bullet Equation for the force of air drag: http://hyperphysics.phy-astr.gsu.edu/hbase/hframe.html
- \bullet Discussion regarding the effect of spin (Magnus effect): http://carini.physics.indiana.edu/E105/spinning-balls.html
- \bullet Discussion about how to calculate the trajectory including air drag: http://www.pdas.com/bb1.htm