Calculation of Ball Trajectories With and Without The Effect of Air Resistance

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Equations of Motion for A Trajectory Without Air Resistance

• The flight of a projectile with initial velocity v_o initial angle θ (with respect to horizontal) is described by the following sets of equations (neglecting air resistance):



Where

 $v_{o,x} = v_o \cos \theta$, $v_{o,y} = v_o \sin \theta$ and the acceleration of gravity $g = 9.81 \text{ m/s}^2$

Thus, there is an analytical solution for the position as a function of time

Equations of Motion for A Trajectory Including Air Resistance

- The flight of a projectile with initial velocity v_o initial angle θ (with respect to horizontal) is described by the following sets of equations (including air resistance):
- Horizontal Motion

$$\frac{\frac{dv_x}{dt} = \frac{f_{drag,x}(t,v_x)}{m}}{\frac{dx}{dt} = V_x(t)}$$

Where the force of drag

Vertical Motion

$$\frac{dv_y}{dt} = a_y = \frac{f_{drag,y}(t, v_y)}{m}$$
$$\frac{dy}{dt} = v_y(t)$$

 $f_{drag}(t) = -\frac{1}{2}C_d \rho Av^2$ where C_d = numerical drag coefficient ≈ 0.5 for a sphere ρ = density of air = 1.225 kg / m³ at sea level $A = cross - \sec tional area = \frac{1}{4}\pi d^2$ for a sphere v = velocity

A numerical solution of the differential equations must be used to get the position information (I used a C++ program to solve them using a 4th order Runga-Kutta method)

Minimum and Maximum Ranges To Fire The Ball At Goal

 $v_o = 12$ m/s, ball diameter = 7", mass of ball = 185 g

Assuming that we would like to used a fixed launch angle to minimize the complications of making adjustments on the fly in the competition, we set the fixed angle such that the peak height of the trajectory allows the ball to pass just below the top of the goal. We can then calculate the minimum and maximum range from which to shoot the ball and still clear the goal. Here are these ranges with and without the effects of air resistance for various heights for the launcher.

	WITHOUT AIR RESISTANCE			WITH AIR RESISTANCE		
Height of Launcher (inches)	Min Range ft	Max Range ft	Optimal Angle degrees	Min Range ft	Max Range ft	Optimal Angle degrees
60	6.4	31.0	25.5	5.8	25.1	27.7
55	7.2	31.5	26.7	6.4	25.4	29.2
50	7.9	32.0	28.0	6.8	26.0	30.6
45	8.6	32.4	29.1	7.4	25.8	32.0

Calculation of The Range That Ball Will Travel With and Without Air Resistance When $\theta = 30^{\circ}$

 $v_o = 12$ m/s, ball diameter = 7", mass of ball = 185 g

	With Drag	W/O Drag	
Height of Launcher	Range	Range	
(inches)	ft	ft	
60	36.3	49.1	
55	35.9	48.4	
50	35.6	48.0	
45	35.2	47.4	
40	34.8	46.8	

From section 4.3.1 of the 2006 FIRST Robotics Competition Documents:

<**S02**> Muzzle Velocity - No ROBOT may throw a ball with an exit velocity of greater than 12 m/s (26.8 mph). As a reference, a ball-traveling at this velocity when leaving the ROBOT at an *angle of 30°* from horizontal with no spin *will travel approximately 35 feet*. A robot that violates this rule will be considered unsafe per <S01>.

Thus, my numerical simulation that included air drag appears to be in agreement with the expectations from FIRST

Optimal Trajectory Without Air Resistance

 $v_o = 12 \text{ m/s}, \ \theta = 25.5 \text{ degrees, height of launcher} = 60"$







References

- Trajectory equations ignoring air resistance: <u>http://hyperphysics.phy-astr.gsu.edu/hbase/traj.html</u>
- Equation for the force of air drag: <u>http://hyperphysics.phy-astr.gsu.edu/hbase/hframe.html</u>
- Discussion regarding the effect of spin (Magnus effect): <u>http://carini.physics.indiana.edu/E105/spinning-balls.html</u>
- Discussion about how to calculate the trajectory including air drag: <u>http://www.pdas.com/bb1.htm</u>